

# The Merits of the Integral **Equation Methods in** Computational **Optoelectronicsics**

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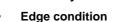


### 2. Fundamentals of Analytical Regularization

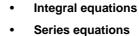
Reduction of EM BVP to a Fredholm's operator equation

#### **Boundary-value problem**

- **Maxwell equations**
- **Boundary conditions**



**Radiation condition** 



Series equations

$$GX = Y$$

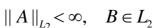


$$G = G_1 + G_2$$

Suppose that:

$$X + AX = B$$

$$A = G_1^{-1}G_2, \quad B = G_1^{-1}Y \quad \begin{array}{c} \text{is more} \\ \text{singular than} \quad G_2 \end{array}$$





and  $G_1^{-1}$  is known



Fredholm 2-nd kind IE or infinite-matrix equation



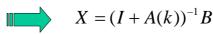
### 3. Consequences of Regularization

### Fredholm's theorems

$$X + A(k)X = B$$

**Existence of exact solution:** 

If operator equation is equivalent to BVP, then its solution is unique for all real wavenumbers k



Point-wise convergence of discrete solutions:

$$e(N) = || X - X^{N} || (|| X ||)^{-1}$$
  
 $\leq || (I + A)^{-1} || \cdot || A - A^{N} || \xrightarrow[N \to \infty]{} 0$ 



Condition number is stable:

$$cond(I + A) = ||I + A|| \cdot ||(I + A)^{-1}|| < \infty$$



### 4. Efficient Regularization Schemes

#### What is invertible?

$$G = G_1 + G_2 \qquad ?G_1$$



• Canonical-shape part (circular-cylinder & sphere)

well developed - trigonometric basis; used for multiple canonical scatterers & in a layered host medium

**Small-contrast part** 

well developed - Muller equations, (loaded) volume IE

• Static part: PEC and imperfect zero-thickness screens well developed - EFIE + Chebyshev basis in 2-D;

variants - in FT domain, RHP (in periodic case)



scarcely developed - most promising for solving big problems of quasioptics with economic algorithms

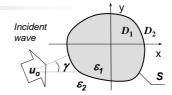




### 5. Dielectric Cylinder Scattering - Formulation

### **Boundary-value problem**

Scattering by an arbitrary smooth dielectric cylinder. Incident field is a plane wave in the reception mode and a directive localized source field in the transmission mode



wavenumber 
$$k_j = k \sqrt{\varepsilon_j \mu_j} \qquad \alpha_j = 1/\mu_j \quad \text{or} \quad 1/\varepsilon_j$$

**2D BVP**: Find 
$$u_j(\vec{r})$$
,  $r \in D_j$   $j=1,2$ , such that

- 1. Helmholtz equation off S:  $(\Delta + k_j^2)u_j^{sc}(\vec{r}) = 0$
- 2. Boundary conditions at S:



$$\left. u_1(\vec{r}) \right|_S = \left. u_2(\vec{r}) \right|_S \quad \text{ and } \quad \alpha_1 \left. \frac{\partial u_1(\vec{r})}{\partial n} \right|_S = \alpha_2 \left. \frac{\partial u_2(\vec{r})}{\partial n} \right|_S$$

3. Sommerfeld radiation condition



# 6. Muller's Boundary Integral Equations

#### **Small contrast inversion**

Fields representation = combination of the single and double layer potentials

$$\begin{aligned} u_{I}(\vec{r}) &= \int_{S} \left[ p_{I}(\vec{r}_{s}) \frac{\partial G_{I}(\vec{r}, \vec{r}_{s})}{\partial n_{s}} - q_{I}(\vec{r}_{s}) G_{I}(\vec{r}, \vec{r}_{s}) \right] dl_{s} & \vec{r} \in D_{1} \\ u_{2}(\vec{r}) &= \int_{S} \left[ q_{2}(\vec{r}_{s}) G_{2}(\vec{r}, \vec{r}_{s}) - u_{2}(\vec{r}_{s}) \frac{\partial G_{2}(\vec{r}, \vec{r}_{s})}{\partial n_{s}} \right] dl_{s} + u_{0}(\vec{r}) & \vec{r} \in D_{2} \end{aligned}$$

Parameterization + Boundary conditions =>

Uniquely solvable set of BIEs of the Fredholm 2<sup>nd</sup> kind :

$$\begin{cases} p_1(t) - \int_0^{2\pi} p_1(t_s) A(t, t_s) dt_s + \int_0^{2\pi} q_1(t_s) B(t, t_s) dt_s = L(t) u_0(t) \\ \left(1 + \frac{\alpha_1}{\alpha_2}\right) \frac{q_1(t)}{2} - \int_0^{2\pi} p_1(t_s) C(t, t_s) dt_s + \int_0^{2\pi} q_1(t_s) D(t, t_s) dt_s = L(t) \frac{\partial u_0(t)}{\partial n} \end{cases}$$





### 7. Muller's Boundary Integral Equations

### Kernel properties & discretization

In one of the kernels, a log-type singularity is kept; others are regular

$$A(t,t_s) = L(t) \left( \frac{\partial G_1}{\partial n_s} - \frac{\partial G_2}{\partial n_s} \right) B(t,t_s) = L(t) \left( G_1 - \frac{\alpha_1}{\alpha_2} G_2 \right) C(t,t_s) = L(t) \left( \frac{\partial^2 G_1}{\partial n_s \partial n} - \frac{\partial^2 G_2}{\partial n_s \partial n} \right)$$

$$||A||, \ldots, ||D|| < (\varepsilon - 1) Const$$
  $D(t,t_s) = L(t) \left( \frac{\partial G_1}{\partial n} - \frac{\alpha_1}{\alpha_2} \frac{\partial G_2}{\partial n} \right)$ 

Computing the singular integrals is improved by adding and subtracting the canonical-circle operators, e.g.  ${\bf G}^0$ 

$$\overset{o}{G} = \frac{i}{4}H_0(2kaSin|(t - t_s)/2|)$$

MBIEs + trigonometric-Galerkin discretization =>Fred.-2 Matrix Equation filled in with <u>DFFT</u>

$$p(t)L(t) = \frac{2}{i\pi} \sum_{m=-\infty}^{\infty} p_n e^{imt}$$



$$\begin{cases} \sum_{m=-\infty}^{\infty} p_m (\delta_{km} + A_{km}) + \sum_{m=-\infty}^{\infty} q_m B_{km} = u_k \\ \sum_{m=-\infty}^{\infty} p_m C_{km} + \sum_{m=-\infty}^{\infty} q_m (\delta_{km} + D_{km}) = \overline{u}_k \end{cases}$$

If the natural parameterization is used: 
$$L(t)=1$$



# 8. MBIE Algorithm Properties

#### Test example: super-ellipse

Homogeneous dielectric cylinder:

«super-ellipse» = rectangle with smoothed edges:

$$(x/la)^{2\nu} + (y/a)^{2\nu} = 1 \quad 0 < \nu < \infty$$

Relative computational error, determined by norm in  $l_2$ 

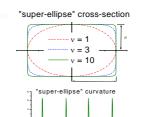
$$e(N) = \frac{\|Z^N - Z^{N+1}\|}{\|Z^N\|}$$

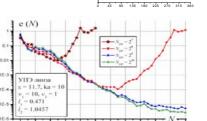
where

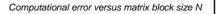
$$Z^N = \left\{ z_n^{1N}, z_n^{2N} \right\}$$

3 digit accuracy is achieved if

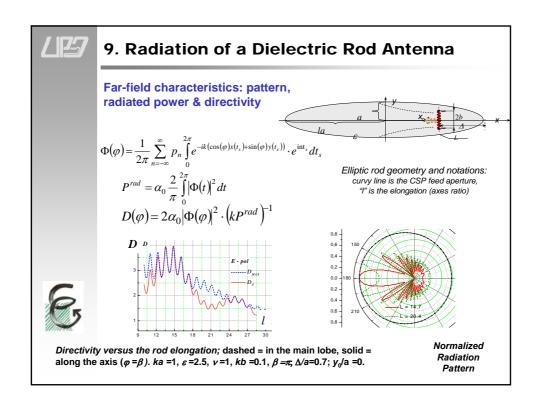
$$N \approx kal\sqrt{\varepsilon} + v + 10$$

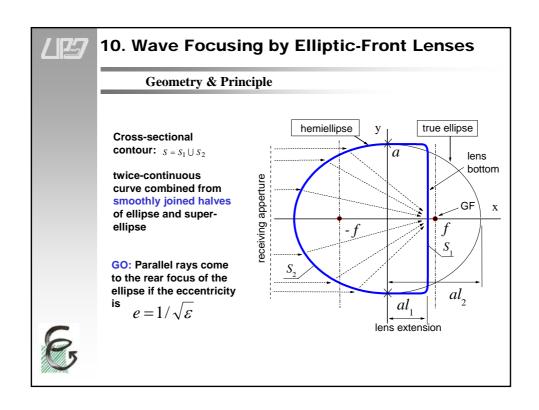


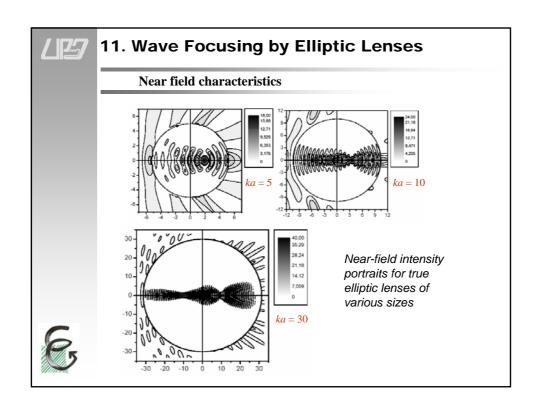


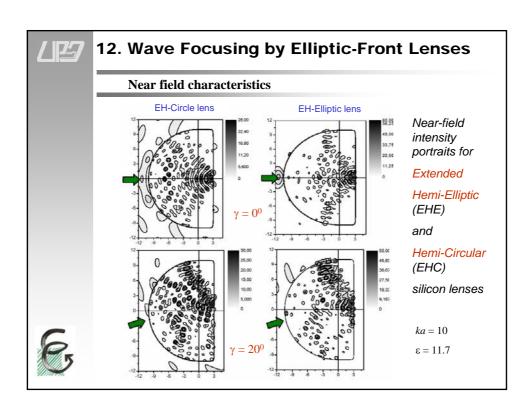


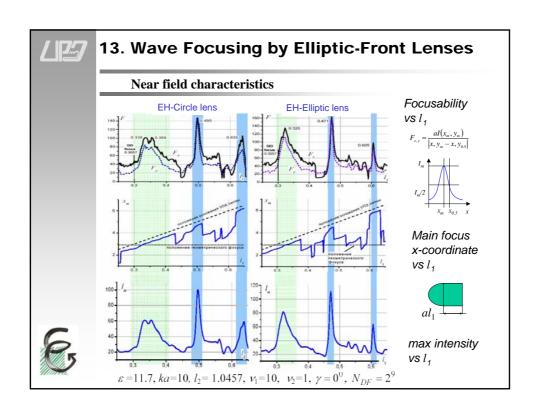


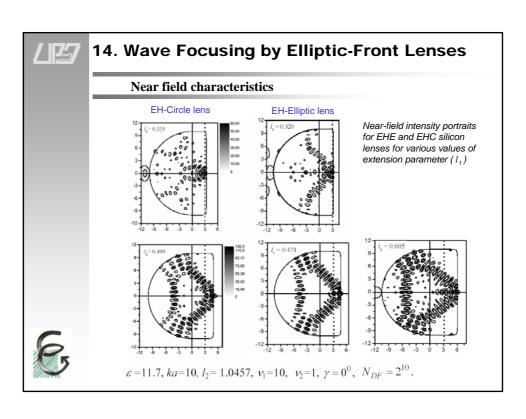


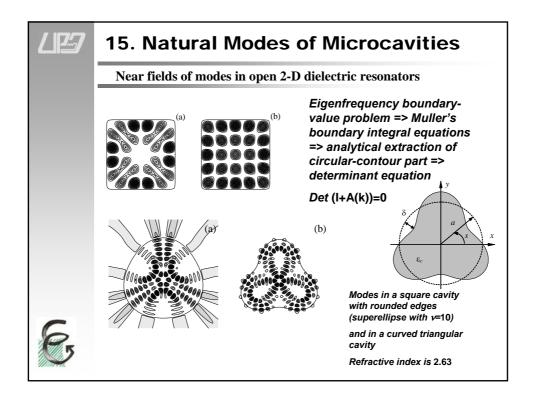










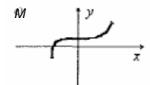




### 16. PEC Strip Scattering - Formulation

### **Boundary-value problem**

Scattering by an arbitrary smooth open cylindrical PEC strip. Incident field is a plane wave in the RCS analysis and a directive localized feed field in the reflector antenna analysis



2-D BVP: find such

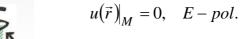
$$u^{sc}(\vec{r}), \quad u = u^{in} + u^{sc}$$
 that

1. Helmholtz equation off M:

$$(\Delta + k^2)u^{sc}(\vec{r}) = 0$$

2. Boundary conditions at M:

$$\frac{\partial u(\vec{r})}{\partial n}\bigg|_{M} = 0, \quad H - pol.$$









### 17. Electric-Field Integral Equations

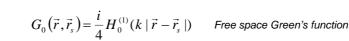
### **Singular Integral Equations**

Fields representation - single/double layer potential:





$$u(\vec{r}) = \int_{M} p(\vec{r}_s) G_0(\vec{r}, \vec{r}_s) dl_s, \quad u(\vec{r}) = \int_{M} q(\vec{r}_s) \frac{\partial}{\partial n_s} G_0(\vec{r}, \vec{r}_s) dl_s$$



Parameterization of contour  $M \Rightarrow$  Boundary conditions  $\Rightarrow$  Singular IEs of the 1<sup>st</sup> kind

$$\int_{-1}^{1} p(t_s) G_0(t, t_s) L(t_s) dt_s = -u^{in}(t), \quad \frac{\partial}{\partial n} \int_{-1}^{1} q(t_s) \frac{\partial}{\partial n_s} G_0(t, t_s) L(t_s) dt_s = -\frac{\partial u^{in}(t)}{\partial n}$$



Direct discretization of SIE does not guarantee convergence, is inefficient and inaccurate



### 18. EFIE & Method of Analytical Preconditioning

Static-part inversion: diagonalization with eigenfunctions



Green's function decomposition =static singular part + regular part

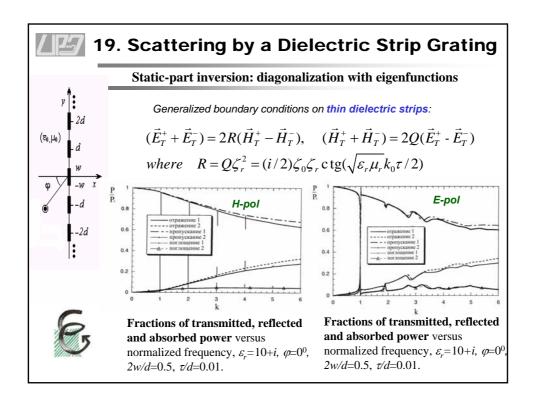
$$G_0(\vec{r}, \vec{r}_s) = \frac{i}{4} \ln |\vec{r} - \vec{r}_s| + R(k |\vec{r} - \vec{r}_s|)$$

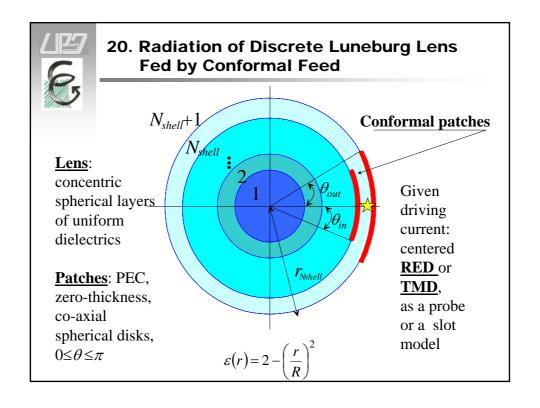
E-pol. 
$$\int\limits_{-1}^{1} \frac{T_n(t_s)}{(1-t_s)^{1/2}} \ln(t-t_s) dt_s = \sigma_n T_n(t), \quad T_n(t) = \qquad \text{Chebyshev polynomials of the 1-st kind}$$
 H-pol.

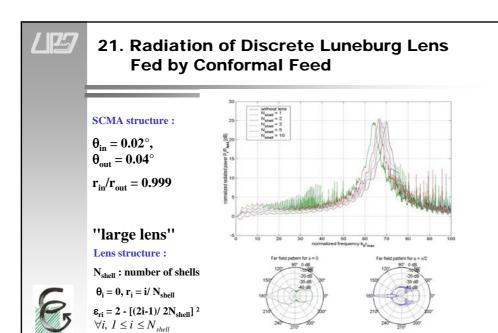
$$\int\limits_{-1}^{1} (1-t_s)^{1/2} U_n \left(t_s\right) \frac{\partial^2 \ln \left(\vec{r}-\vec{r}_s\right)}{\partial n^2} \Bigg|_{M} dt_s = \tau_n U_n(t), \quad U_n(t) = \quad \begin{array}{c} \text{Chebyshev polynomials} \\ \text{of the 2-nd kind} \end{array}$$



To transform SIE to the Fredholm 2<sup>nd</sup> kind matrix equation, take full set of the corresponding polynomials as a basis (I.e., make analytical preconditioning)







Lens => small shift of SCMA resonance + whispering-gallery modes



### 22. Conclusions: Merits of Analytical Regularization of Integral Equations

- 1. Generates convergent and economic scattering algorithms with easily controlled accuracy
- 2. Leads to reliable simulations that predict even finest field features
- 3. Easily accesses quasioptical range
- 4. Is promising for CG iterative solvers
- 5. Can serve as a fast core for optimization
- 6. Enables explicit asymptotic solutions



7. Reduces eigenvalue problems to favorable determinant equations